

# 11. Automata and languages, cellular automata, grammars, L-systems

## 11.1 Automata and languages

*Automaton* (pl. *automata*): in computer science, a simple *model* of a machine or of other systems. (→ a simplification of real machines or systems)

Examples:

Some systems to be modelled as automata with finite description

Example 1: Traffic lights, with a timer for stepping from state to state; outputs switch on or off the different lamps.

**Inputs:** Timer ( $t$ )

**Outputs:** switch to red (red), switch to red and yellow (red-and-yellow), switch to green (green), switch to yellow (yellow).

**States:** red, red-and-yellow, green, yellow

Example 2: A cookie vending machine.

**Inputs:** a coin ( $c$ ); buttons for choosing some sort of cookies ( $b_1$ ), ( $b_2$ ) or for wanting the money back (back).

**Outputs:** a coin back ( $c$ ); and for giving out one of several kinds of cookies ( $c_1$ ), ( $c_2$ ); an error signal (bell).

**States:** waiting ( $w$ ); coin-accepted ( $c$ )

### Example 3: A sugar-digesting bacterium

**Inputs:** glucose ( $g$ ), lactose ( $l$ ), nothing ( $n$ )

**Outputs:** lactase gene activated ( $a$ ), lactase gene inactive ( $i$ ) – can be measured in the laboratory by methods from molecular genetics

**States:** lactose-digesting (1), glucose-digesting (2), dormant (3)

### Abstract notion: the *Mealy automaton*

What do the examples have in common?

Approach: A **finite set** of inputs, a **finite set** of outputs, and a **finite set** of states. At any moment, the system is in one state.

Formally: **Mealy automaton**

A **Mealy automaton** is a tuple

$$(Q, \Sigma, \Delta, \delta, \lambda, q_0)$$

where  $Q$  is a finite set (the set of **states** of the automaton),  $\Sigma$  is the **input alphabet**,  $\Delta$  is the **output alphabet**,  $\delta : Q \times \Sigma \rightarrow Q$  is a *transition function*,  $\lambda : Q \times \Sigma \rightarrow \Delta$  is an **output function**, and  $q_0 \in Q$  is the **initial state**.

(remember:  $\delta : Q \times \Sigma \rightarrow Q$  means that the function  $\delta$  associates to each *pair*  $(q, s)$  with  $q$  from  $Q$ ,  $s$  from  $\Sigma$  an element  $\delta(q, s) \in Q$ . For  $\lambda$  analogously.)

**Interpretation:**  $Q$  models the **different states** the system can be in, and  $q_0$  is the state it starts in.  $\Sigma$  models the **different inputs** on which the system can react, and  $\Delta$  models the **different ways in which the system can react** on an input.  $\delta$  models the **change of the state** which can happen when an input event takes place: if the system is in state  $q$  and input  $\sigma$  is entered in the system, the system enters state  $\delta(q, \sigma)$ .  $\lambda$  models the reaction of the system: If the system is in state  $q$  when an input  $\sigma$  is entered, the system outputs  $\lambda(q, \sigma)$ .

The set of outputs  $\Delta$  might include a do-nothing action, which can be used for combinations of states and inputs in which no output is generated.

A Mealy automaton can be understood as a **translator**: each word of letters from  $\Sigma$  is translated to a word of letters from  $\Delta$  of the same length.

Example for a Mealy automaton: The cookie vending machine from above.

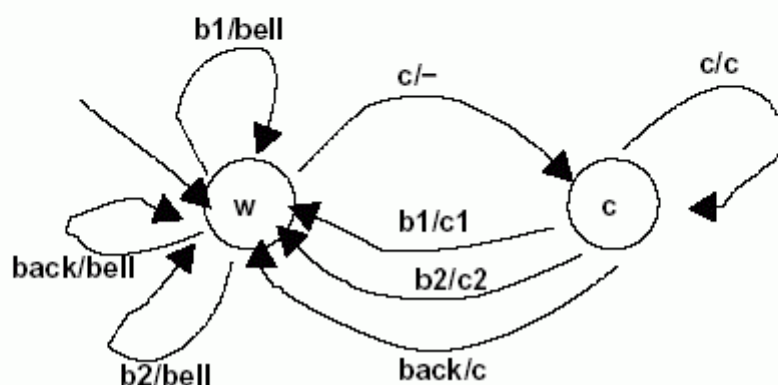
Model:  $(\{w, c\}, \{c, b_1, b_2, \text{back}\}, \{c, c_1, c_2, \text{bell, nothing}\}, \delta, \lambda, w)$

with  $\delta$  and  $\lambda$  defined by the following table:

$q$	$\sigma$	$\delta(q, \sigma)$	$\lambda(q, \sigma)$
$w$	$c$	$c$	nothing
$w$	$b_1$	$w$	bell
$w$	$b_2$	$w$	bell
$w$	back	$w$	bell
$c$	$c$	$c$	$c$
$c$	$b_1$	$w$	$c_1$
$c$	$b_2$	$w$	$c_2$
$c$	back	$w$	$c$

There must be a follower state and an output **for each state/input combination**.

Graphical representation: Initial state marked an incoming arrow not starting at a state. Each  $Q$  represented as a circle.  $\delta$  and  $\lambda$  represented as arrows between circles, which are labeled with a pair of form  $\Sigma/\Delta$ . Each line in the tabular representation corresponds to an arrow:



### Formal languages:

**Formal language:** (short: language) Set of **words** (=character sequences) over an **alphabet**  $\Sigma$  (=a finite set, interpreted as set of characters)

Examples:

$\Sigma_1 = \{a, b, \dots, z\}$ , with language  $L_1 = \{\text{one, two, three}\}$

$\Sigma_2 = \{0, 1\}$  with language  $L_2 = \{\epsilon, 0, 1, 00, 01, 10, 11, 000, \dots\}$   
 ( $L_2$  contains all sequences of 0's and 1's of finite length, even the empty sequence, denoted  $\epsilon$ , of length zero.)

$\Sigma_3 = \{0, 1\}$  with language

$L_3 = \{w \in \Sigma_3^* \mid \text{The number of 1's in } w \text{ is positive and even}\}$

Definitions concerning words and formal languages:

The *length*  $|w|$  of a word  $w$  is the number of its letters.  
The length of the empty word  $\varepsilon$  is 0.

The language of *all* finite words over an alphabet  $\Sigma$ , including the empty word, is denoted by  $\Sigma^*$ .

(In the example above:  $L_2 = \Sigma_2^*$  .)

The language of all *non-empty* words over  $\Sigma$  is denoted by  $\Sigma^+$ .  $\Sigma^+ = \Sigma^* - \{\varepsilon\}$ .

The language of all words of length  $n$  over  $\Sigma$  is denoted by  $\Sigma^n$ .  $\Sigma^0 = \{\varepsilon\}$ .

### Operations on formal languages

Let  $L$ ,  $L_1$  and  $L_2$  be languages over a common alphabet  $\Sigma$ . Then we can define the following other languages over  $\Sigma$ :

- $L^*$  is the set of words  $w$  over  $\Sigma$  which can be split into a finite number of sub-words  $w_1w_2 \dots w_n$  such that each  $w_i \in L$ . The empty sequence of words is allowed, i.e.  $\varepsilon \in L^*$ .
- $L^+$  is defined similar to  $L^*$ , only the empty sequence of subwords is not allowed.  $\varepsilon$  is in  $L^+$  only if it is already in  $L$ .
- $L_1L_2$  is defined as the set of words  $w$  which can be split into two sub-words  $w = w_1w_2$  with  $w_1 \in L_1 \wedge w_2 \in L_2$ .

The connection between automata and formal languages:

How can we define a language using an automaton?

*First idea:* collect all input sequences for which the corresponding output of the automaton ends with a special symbol "accept".

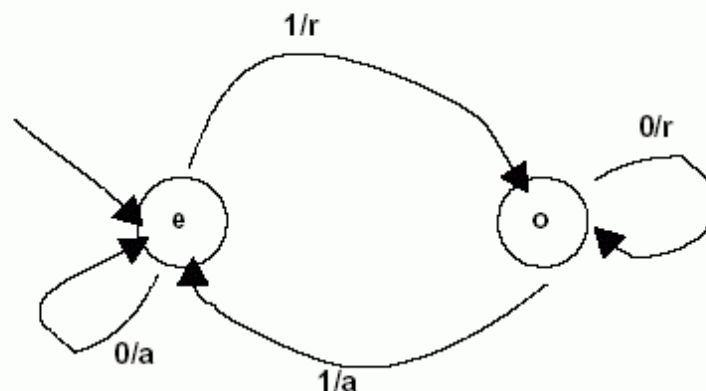
→ Formal language definition by Mealy automata:

Consider a Mealy automaton with  $\Delta = \{a, r\}$  (for 'accepted' and 'rejected').

The language  $L(M)$  over the input alphabet  $\Sigma$  defined by a Mealy automaton  $M$  consists of all words  $w \in \Sigma^*$  such that when  $w$  is processed, the last output symbol is  $a$ .

Example:

A Mealy automaton which accepts  $L_3$  (words from  $\{0, 1\}$  with an even and positive number of ones):



Problem: Languages which contain  $\epsilon$  can not be defined in this way.

We simplify the notion of automaton:

The output is no longer necessary, only the states are used.

→ notion of "*finite automaton*" (FA); also called "deterministic finite automaton" (DFA):

A finite automaton is a quintuple

$$(Q, \Sigma, \delta, q_0, F)$$

with  $Q$  a finite set (the **states** of the DFA),  $\Sigma$  the *input alphabet*,  $\delta : Q \times \Sigma \rightarrow Q$  the *transition function*,  $q_0$  the **initial state** and  $F \subseteq Q$  the set of **final states**.

Difference to Mealy automata: There is no output alphabet and no output function; but there is a set of final states.

A FA is an "acceptor": Input words (i.e. elements of  $\Sigma^*$ ) which lead the automaton from  $q_0$  to an element of  $F$  are *accepted* by the automaton, other input words are **rejected**.

Extension of  $\delta$  to words:  $\hat{\delta}$

$$\hat{\delta} : Q \times \Sigma^* \rightarrow Q$$

with

- $\hat{\delta}(q, \epsilon) = q$
- for each word  $aw \in \Sigma^+$  starting with some letter  $a \in \Sigma$  and continuing with word  $w$ :

$$\hat{\delta}(q, aw) = \hat{\delta}(\delta(q, a), w)$$

Language accepted of a FA  $M$ :

$$L(M) = \{w \in \Sigma^* \mid \hat{\delta}(q_0, w) \in F\}$$

The set of languages which are accepted by some FA are denoted as  $\mathcal{L}_{fa}$ .

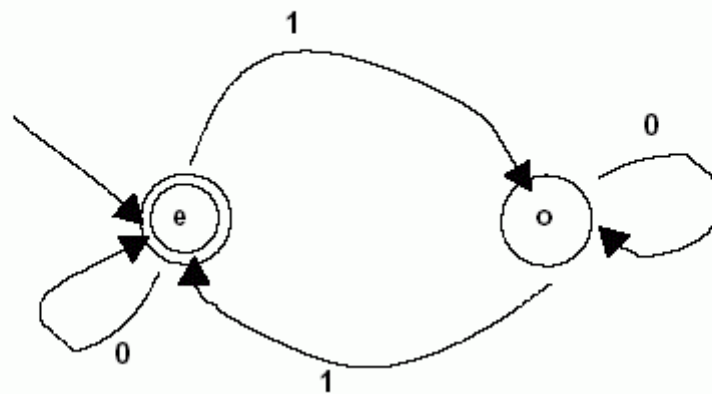
Example of a FA which recognizes all words over  $\{0, 1\}$  with an even number of 1's:

$$(\{e, o\}, \{0, 1\}, \delta, e, \{e\})$$

with  $\delta$  defined by

$q$	$\sigma$	$\delta(q, \sigma)$
$e$	0	$e$
$e$	1	$o$
$o$	0	$o$
$o$	1	$e$

Graphical representation: No outputs; final states as double circles:



FA can be used to *check the correctness* of statements in simple programming languages ("accept" = input was syntactically correct; "reject" = an error was detected). However, more complicated languages need other, more refined forms of automata.

The languages for which a finite automaton exists form a special class of languages:

### Regular languages

A language  $L$  is called **regular** if and only if there is a FA  $M$  with  $L = L(M)$



## *Regular expressions over an alphabet $\Sigma$*

= a way to define "allowed" character sequences (or sequences of commands...), also used e.g. in search queries in databases or information systems  
– *stand in connection with regular languages*

We give a recursive definition:

- If  $a \in \Sigma$ , then  $a$  is a r.e. (one-word/one-letter language)
- $\{\}$  is a r.e. (empty language)
- If  $r$  is a r.e., then  $(r^*)$  is a r.e. (repetition)
- If  $r$  and  $s$  are r.e., then  $(rs)$  is a r.e. (concatenation)
- If  $r$  and  $s$  are r.e., then  $(r|s)$  is a r.e. (alternative)
- No other expressions are r.e.

If parentheses are dropped:  $*$  binds tighter than concatenation, which binds tighter than  $|$ .

The language  $L(t)$  of a regular expression  $t$

$L(t)$  is defined in the following way:

- If  $t = a$  for  $a \in \Sigma$ , then  $L(t) = \{a\}$ .
- If  $t = \{\}$ , then  $L(t) = \{\}$ .
- If  $t = (r^*)$  for some r.e.  $r$ , then  $L(t) = (L(r))^*$
- If  $t = (rs)$  for some r.e.s  $r$  and  $s$ , then  $L(t) = L(r)L(s)$ .
- If  $t = (r|s)$ , for some r.e.s  $r$  and  $s$ , then  $L(t) = L(r) \cup L(s)$ .

The languages which are definable by regular expressions are denoted by  $\mathcal{L}_{re}$ .

### Examples for regular expressions

All sequences of 0's and 1's:  $(0|1)^*$

All nonempty sequences of 0's and 1's:  $(0|1)^* (0|1)$

$\{\epsilon\}$ :  $\{\}^*$

Sequences of 0's and 1's with at least one pair of contiguous 1's:  
 $(0|1)^* 11(0|1)^*$

The language with the two words 000 and 111:  $000|111$

Sequences of 0's and 1' with an even number of 1's:  $(0^* 10^* 1)^* 0^*$

Floating point numbers, using abbreviation  $Z$  for  $(0|1|2|3|4|5|6|7|8|9)$ :

$(\{\}^* | + | -)(ZZ^*)(\{\}^* | (.ZZ^*))(\{\}^* | E(\{\}^* | + | -)ZZ^*)$

The connection to regular languages (i.e., to finite automata):

Theorem:

*The languages which can be defined by regular expressions are exactly the regular languages.*

$$\mathcal{L}_{fa} = \mathcal{L}_{re}$$

This justifies the word "regular" for languages definable by FA.

Proof: by construction of FAs for each of the alternatives for the construction of regular expressions, and vice versa.

Summary of this section:

**Mealy automata:** Some systems are adequately modeled by a *finite number of states*, reacting in each state on one of a *finite number of inputs*, by changing the state and emitting one of a **finite number of output symbols**.

**Formal languages:** sets of finite words over a fixed alphabet.

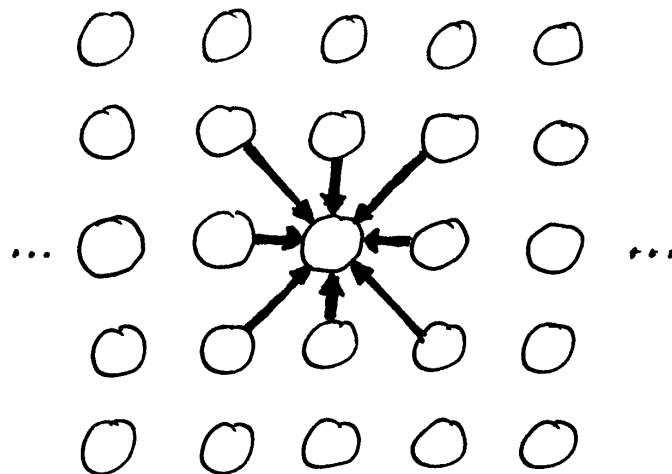
**Finite automata:** Some formal languages are definable by automata. Special kind of automata, specifically for language definition: FA.

**Regular expressions:** An often more convenient way to define the same languages.

## 11.2 Cellular Automata

What will happen if we connect several finite automata with each other?

- A 2-dimensional *Cellular Automaton* (CA) is a rectangular (potentially infinite) array of cells. In each of the cells there is a finite automaton ( $\rightarrow$  each cell can adopt a finite number of states).
- All the automata in the cells have the same functioning.
- In each time step, each cell takes as input the states of all its neighbour cells and uses them to calculate its own new state (using a "transition function").
- The output of the CA is in each time step the pattern of the states of all the cells.



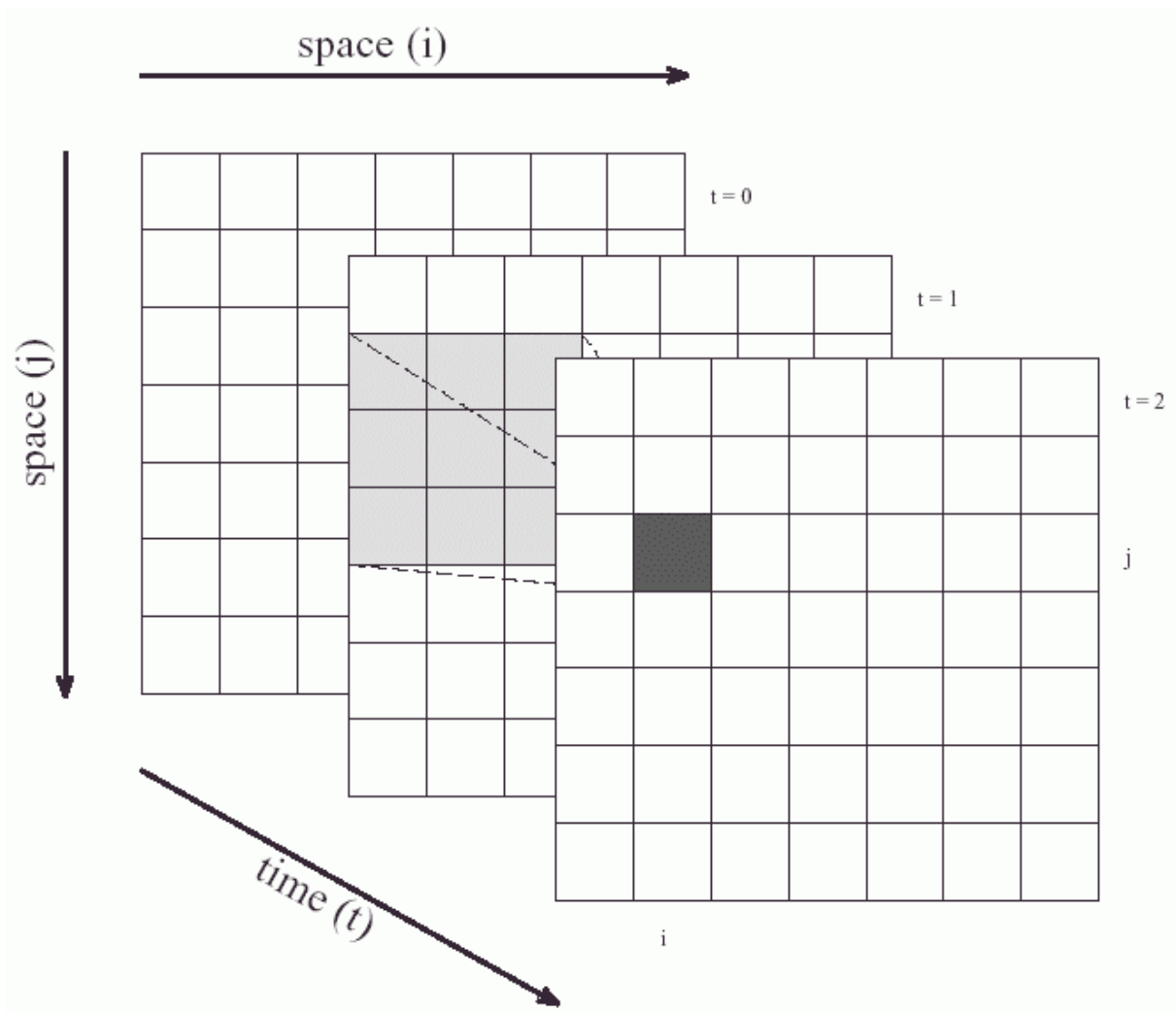
Formally:  $(G, Q, \delta, c)$

$G_{(i,j)}$  : grid of cells with indices  $i, j$

$Q$  : set of states

$\delta: Q^{n+1} \rightarrow Q$  transition function (works in each cell)  
( $n$  = size of the neighbourhood)

$c: G \rightarrow Q$  initial configuration



1- dimensional, 3-dimensional ... CA can be defined analogously. Sometimes also triangular or hexagonal grids are used.

An example of a 2-dimensional CA:  
*Conway's "Game of Life"*

Only 2 states: 1 = "living", 0 = "dead".

Neighbourhood: 8 cells (as above).

Simple transition rule, counting only the number of living cells in the neighbourhood as input.

Living cell, surrounded by 2 or 3 living cells → living

Dead cell, surrounded by exactly 3 living cells → living

in all other cases → dead

## Expressed in other words:

- The **world** is structured like an infinite chess board; on each cell, there either **is** an individual, or there is **no individual**.
- The **time** proceeds in cycles (generations). In each generation, some individuals **die**, others **stay alive**, and in some empty cells, new individuals **are born**.
- The **conditions** for death and birth are: only the **current** state of a cell and that of the **neighbors** are relevant for the state of the cell in the next cycle.

The neighborhood consists of the **eight surrounding cells**.

– An individual **stays alive** if it has **two or three** living neighbors; otherwise, the individual **dies**.

– In an empty cell, an individual is born if there were **three** living neighbors during a cycle.

**Example developments** (environment is assumed to be empty)

Flip forth and back:

```
  | |      |X|      | |  
-+-+-     -+-+-     -+-+-  
X|X|X  -> |X|  -> X|X|X  -> ...  
-+-+-     -+-+-     -+-+-  
  | |      |X|      | |
```

Steady state:

```

| | |   | | |   | | |
-+-+-+ -+-+-+ -+-+-+
|x|x|   |x|x|   |x|x|
-+-+-+ -> -+-+-+ -> -+-+-+ -> ...
|x|x|   |x|x|   |x|x|
-+-+-+ -+-+-+ -+-+-+
| | |   | | |   | | |

```

Move to south-east in four steps:

```

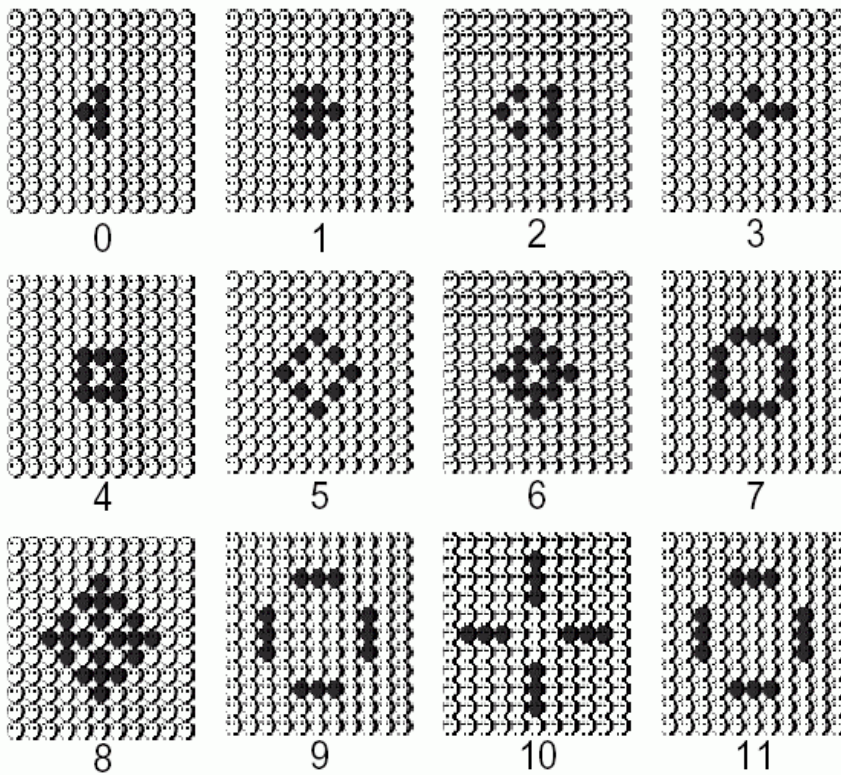
| |x| | | |   |x| | | | |   | |x| | | |   | | | | | | |   | | | | | | |
-+-+-+ -+-+-+ -+-+-+ -+-+-+ -+-+-+
x| |x| | | |   | |x|x| | | |   | | |x| | | |   |x| |x| | | |   | | |x| | | |
-+-+-+ -+-+-+ -+-+-+ -+-+-+ -+-+-+
|x|x| | | |   |x|x| | | |   |x|x|x| | | |   | |x|x| | | |   |x| |x| | | |
-+-+-+ -+-+-+ -+-+-+ -+-+-+ -+-+-+
| | | | | | |   | | | | | | |   | | | | | | |   | |x| | | | |   | |x|x| | | |

```

this configuration is called a "glider".

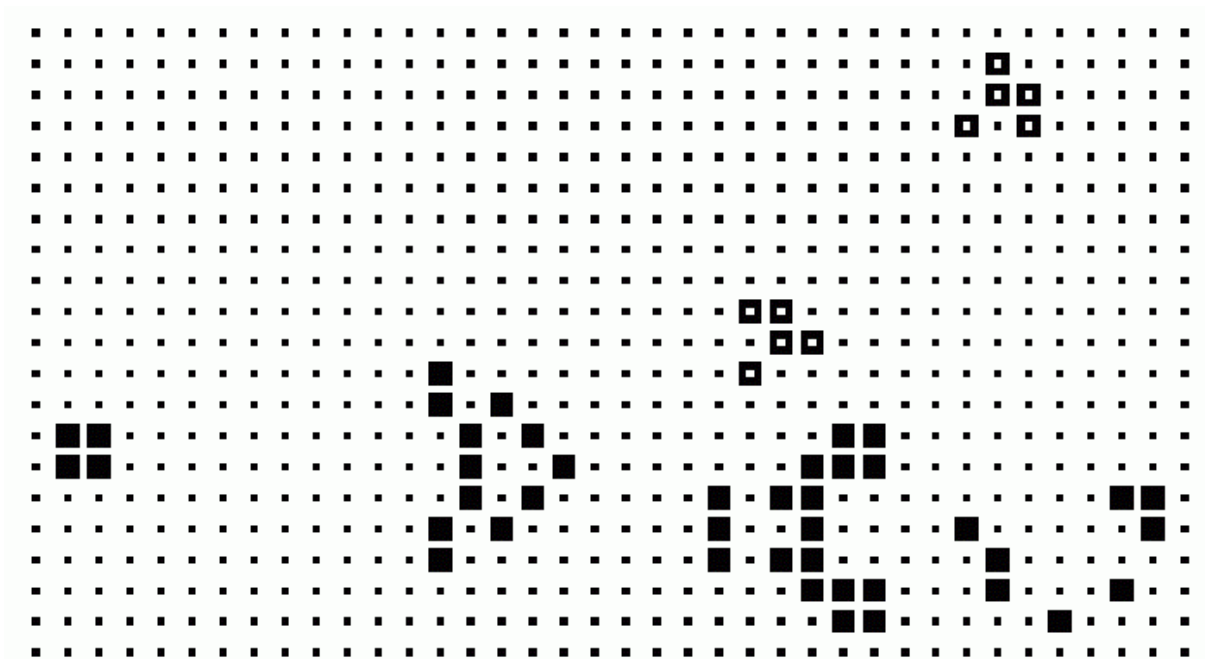
What else can happen in this simple "world"?

Other example development:



→ ends in a periodic pattern.

"Glider gun" (dark) emitting "gliders" (brighter):



Computer scientists have shown that the Game of Life can even simulate a computer with logical circuits (AND, OR, NOT - switches) – hence all what can be calculated can be calculated using the Game of Life!

But: Game of Life rules do not reflect real-world properties  
→ no significance for real-world ecological modelling

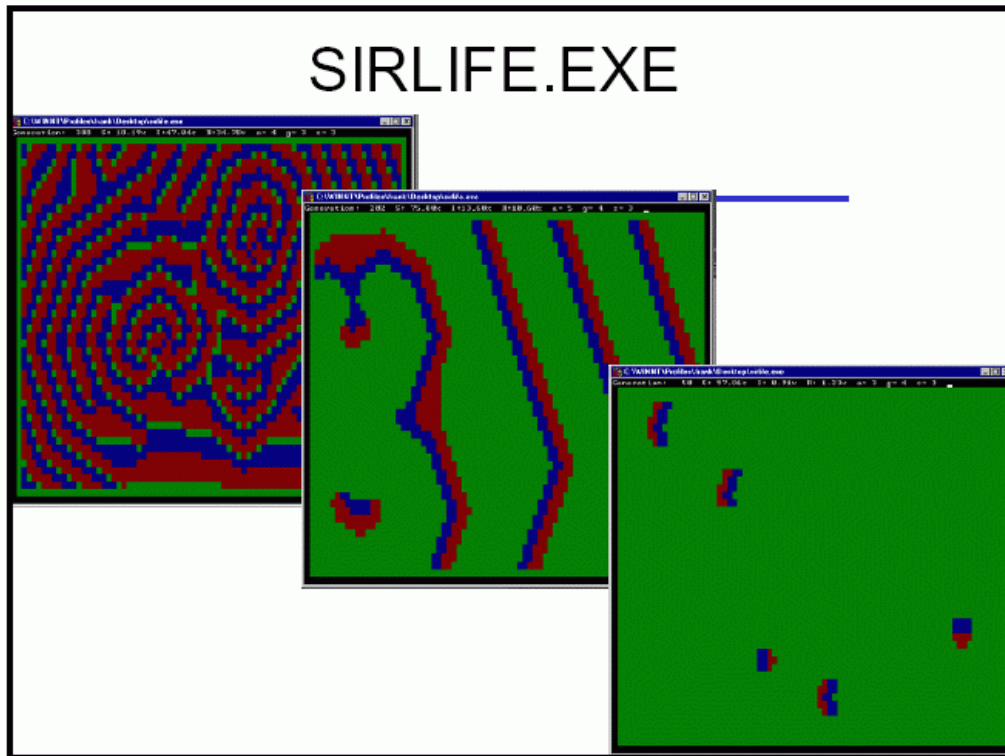
Using more states and other sets of transition rules, cellular automata can be designed *to simulate real-world spatial patterns and dynamics*.

Examples:

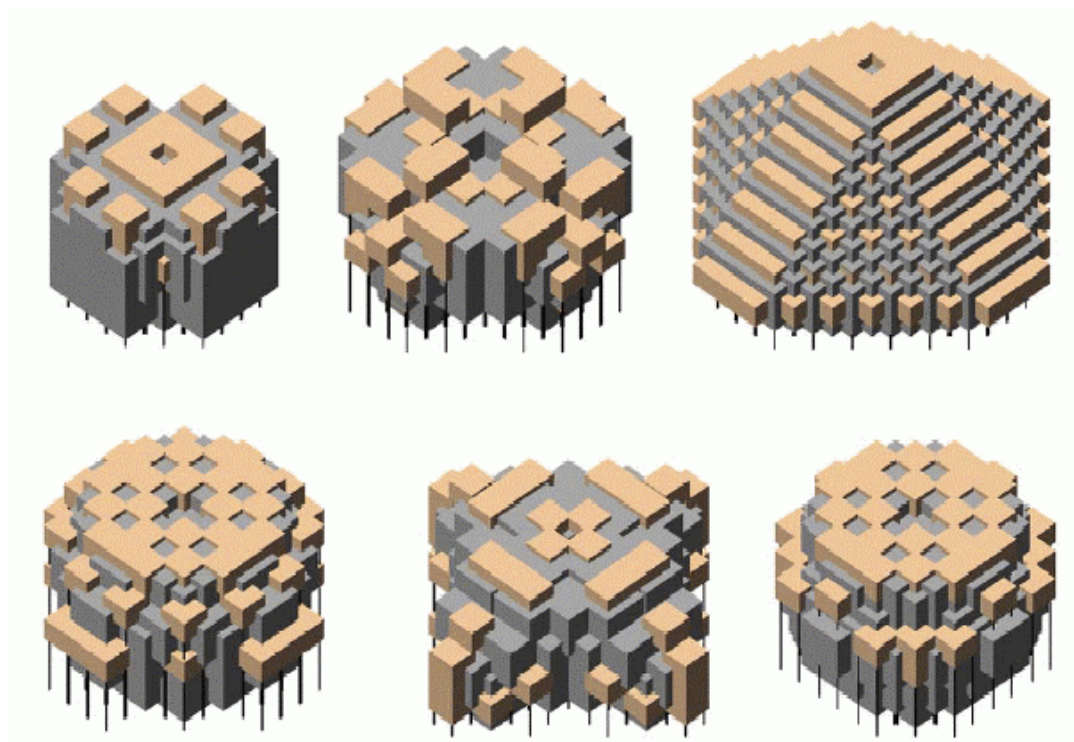
- spreading of forest fires
- spreading of rabies disease in fox populations
- colonisation of a habitat by a new species
- formation of colour patterns on seashells
- chemical reaction patterns
- architecture...



Example: CA simulating the spreading of an epidemic  
(University of Leipzig)



Example: Architectural interpretation of a 3-dimensional  
CA (Robert J. Krawczyk, <http://www.iit.edu/~krawczyk/rjkg03.pdf>)



Disadvantages of CA in simulation applications:

- only discrete time steps
- some directions in space are preferred (due to the underlying grid)
- limited speed of interaction – no far-reaching, immediate effects possible

### 11.3 Grammars

Idea: Complex structures, e.g. the sentences of our natural language, can be described by simple rules.

For example, many sentences have the form:  
Subject - predicate - object.

Definition:

A *Chomsky grammar* is a quadruplet

$$(\Sigma_N, \Sigma_T, X, R),$$

where  $\Sigma_N$  and  $\Sigma_T$  are disjoint sets of symbols,  $X \in \Sigma_N$  and  $R$  is a finite set of rules of the form  $A \rightarrow B$

where  $A$  and  $B$  are words over the alphabet  $\Sigma_N \cup \Sigma_T$  and  $A$  contains at least one symbol from  $\Sigma_N$ .

(after Noam Chomsky, American linguist and philosopher)

Symbols from  $\Sigma_N$  are called *nonterminal symbols*, those from  $\Sigma_T$  *terminal symbols*.

$X$  is the *start symbol*.

A *derivation* of a grammar is a sequence of words, beginning with  $X$ , where each word is obtained from its predecessor by replacing a subword according to one of the rules.

The *language defined by the grammar* consists of all words which can be derived from  $X$  and contain only terminal symbols.

Example:

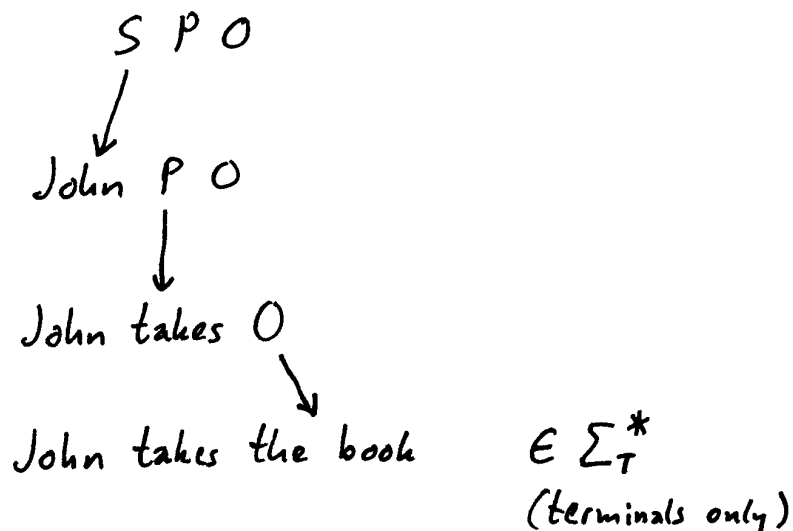
$$\Sigma_N = \{ S, P, O \}$$

$$\Sigma_T = \{ \text{Mary, John, takes, reads, the book,} \\ \text{the newspaper, the apple} \}$$

$$X = SPO$$

$$R = \{ S \rightarrow \text{Mary}, S \rightarrow \text{John}, \\ P \rightarrow \text{takes}, P \rightarrow \text{reads}, \\ O \rightarrow \text{the book}, O \rightarrow \text{the newspaper}, O \rightarrow \text{the apple} \}$$

A derivation:



Applications:

- description of the syntax of natural languages
- precise definition of the syntax of programming languages
- use of grammar-based derivations as an alternative approach to problem-solving, particularly in Artificial Intelligence applications (automated theorem proving, decision-making, speech recognition, games...): rule-based programming paradigm

## 11.4 L-Systems

L-systems = Lindenmayer systems

(after Aristid Lindenmayer, botanist)

special sort of grammars

designed for modelling the shape of organisms,  
particularly plants

Differences to Chomsky grammars:

- no distinction between terminal and nonterminal symbols
- only 1 symbol on the left-hand side of each rule
- all symbols for which a rule is applicable are replaced in parallel
- additional component: an interpretation which assigns a geometrical meaning to each generated word.

Formally:

$$(\Sigma, X, R, I),$$

where  $\Sigma$  is a set of symbols,  $X \in \Sigma$  and  $R$  is a finite set of rules of the form  $a \rightarrow B$

where  $a$  is a symbol from  $\Sigma$  and  $B$  a word over the alphabet  $\Sigma$

$I$  is an interpretation mapping  $I : \Sigma^* \rightarrow \mathbf{R}^3$  (from the set of words into 3-dimensional space).

normally used for the interpretation:

"turtle geometry"

"Turtle": device for drawing or constructing lines or cylindrical elements (virtual)

- stores (graphical and other) information
- has an internal "stack memory" (last in - first out)

- current state of the turtle contains information about current line thickness, step length, colour to be used, further properties of the object which will be constructed next

Turtle *commands* (selection):

**F** "Forward", including construction of an element (line segment, internode of a plant...) uses the current step length as the length of the new segment

**f** forward without construction ("move" command)

**L(x)** change the current step length to  $x$

**L+(x)** increment the current step length by  $x$

**L\*(x)** multiply the current step length by  $x$

**D(x), D+(x), D\*(x)** analogous for thickness (diameter of the next segment)

**RU(45)** Rotation of the turtle around the "up" axis by  $45^\circ$

**RL(...), RH(...)** analogously around the "left" and "head" axis

*up-, left- and head* axis form an orthonormal system with positive orientation which is carried by the turtle

**+, -** abbreviations for **RU( $\varphi$ )** and **RU( $-\varphi$ )** with fixed angle  $\varphi$

*Branching*: Realized with "stack commands"

**[** put current state on the stack memory

**]** take the state from the memory which was just put there and make it the current state of the turtle (finishes a branch)

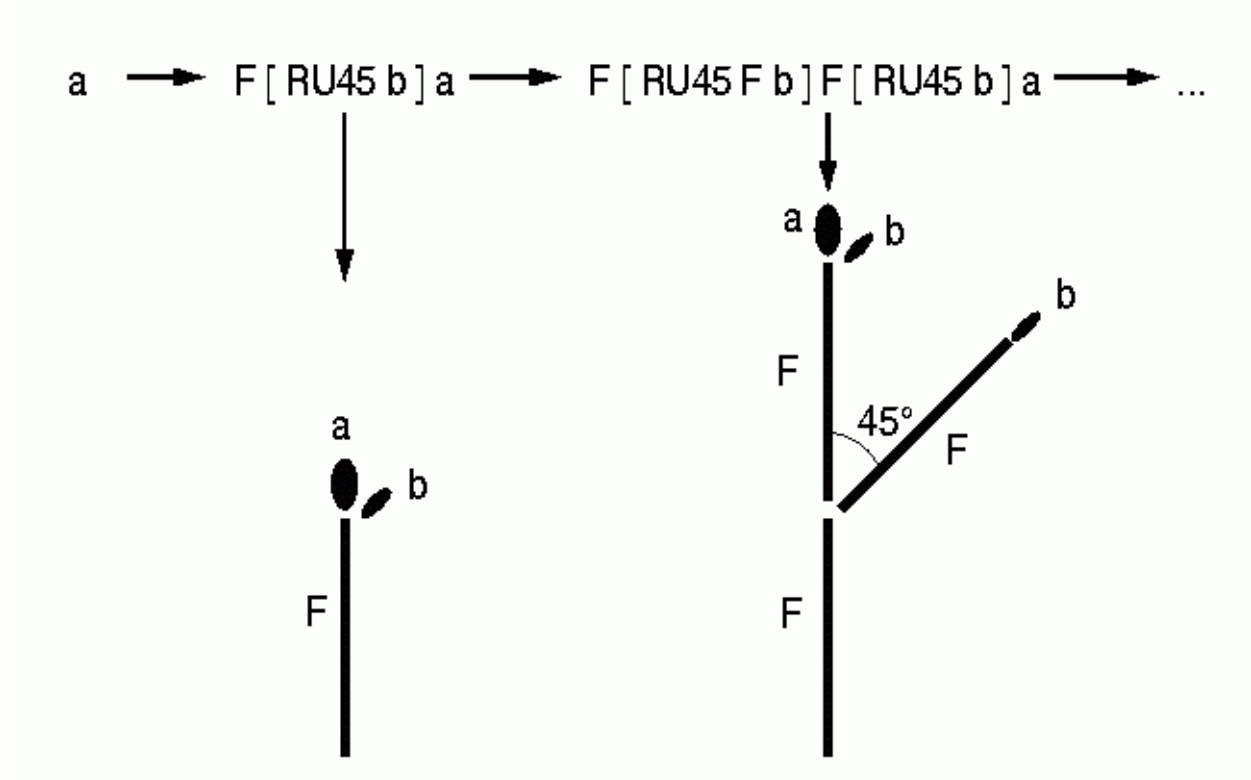
Example:

Rules

$a \rightarrow F [ RU45 b ] a,$

$b \rightarrow F b$

Start word  $a$



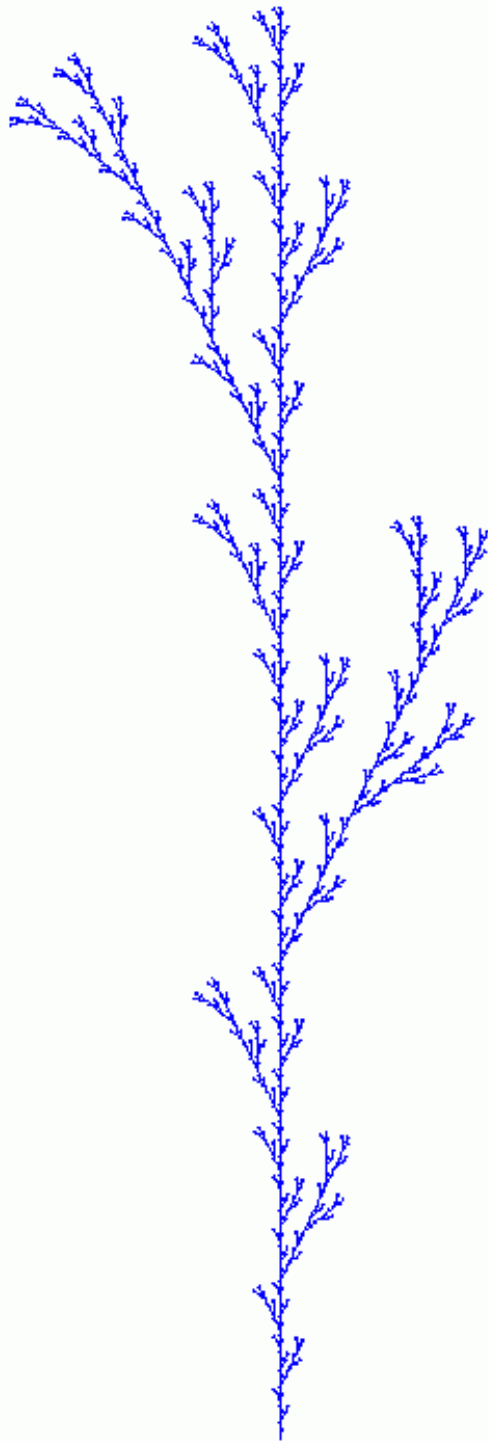
( $a$  and  $b$  are normally not interpreted geometrically.)

Further examples:

`\angle 25.7,`

`F → F [ + F ] F [ - F ] F`

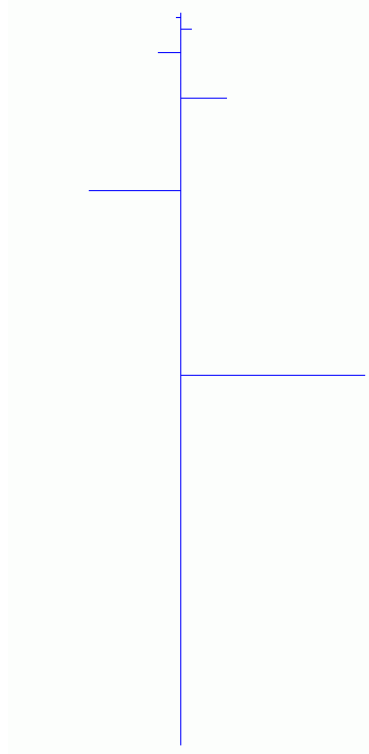
Result after 7 steps:



Branching, alternating orientation of branches and progressive shortening (like in real plants):

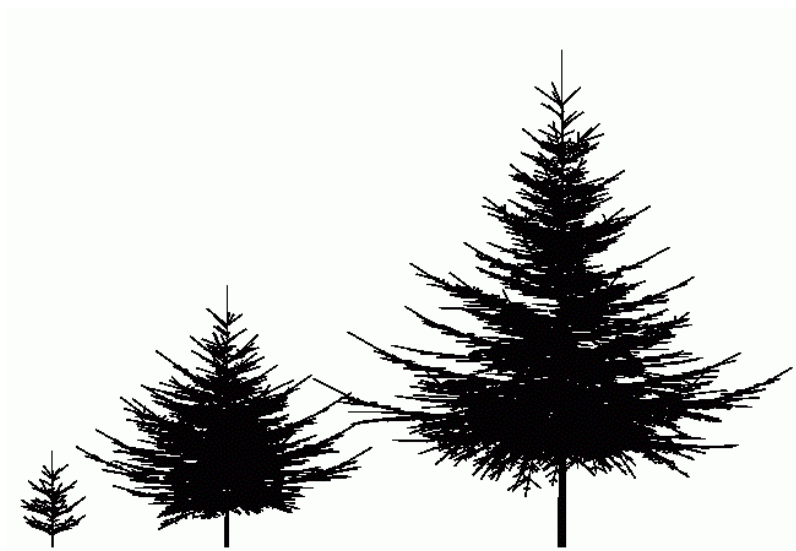
$* \rightarrow F a,$

$a \rightarrow L*0.5 [ RU90 F ] F RH180 a$

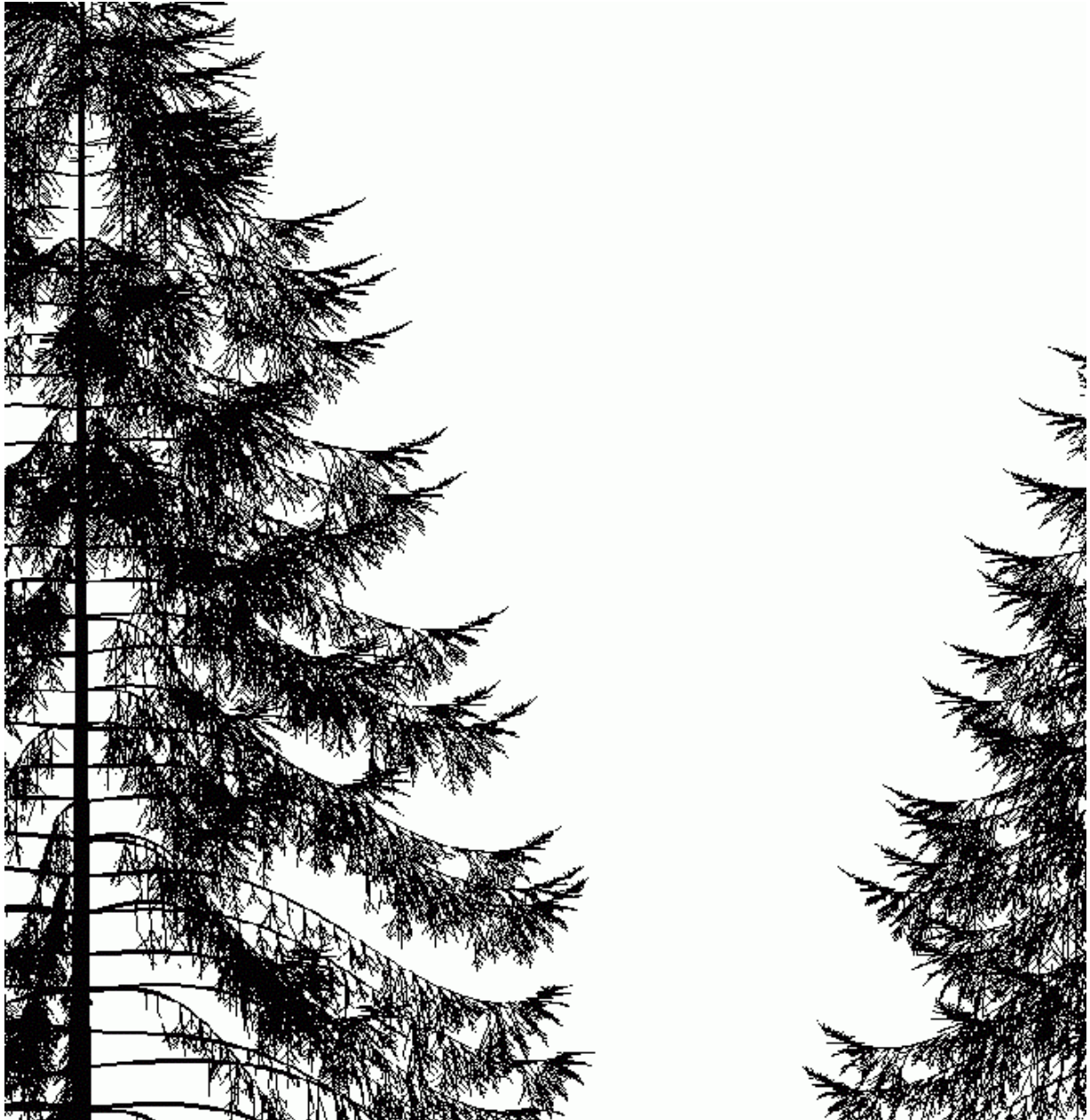


Examples of real-world vegetation modelled with L-systems:

spruce trees



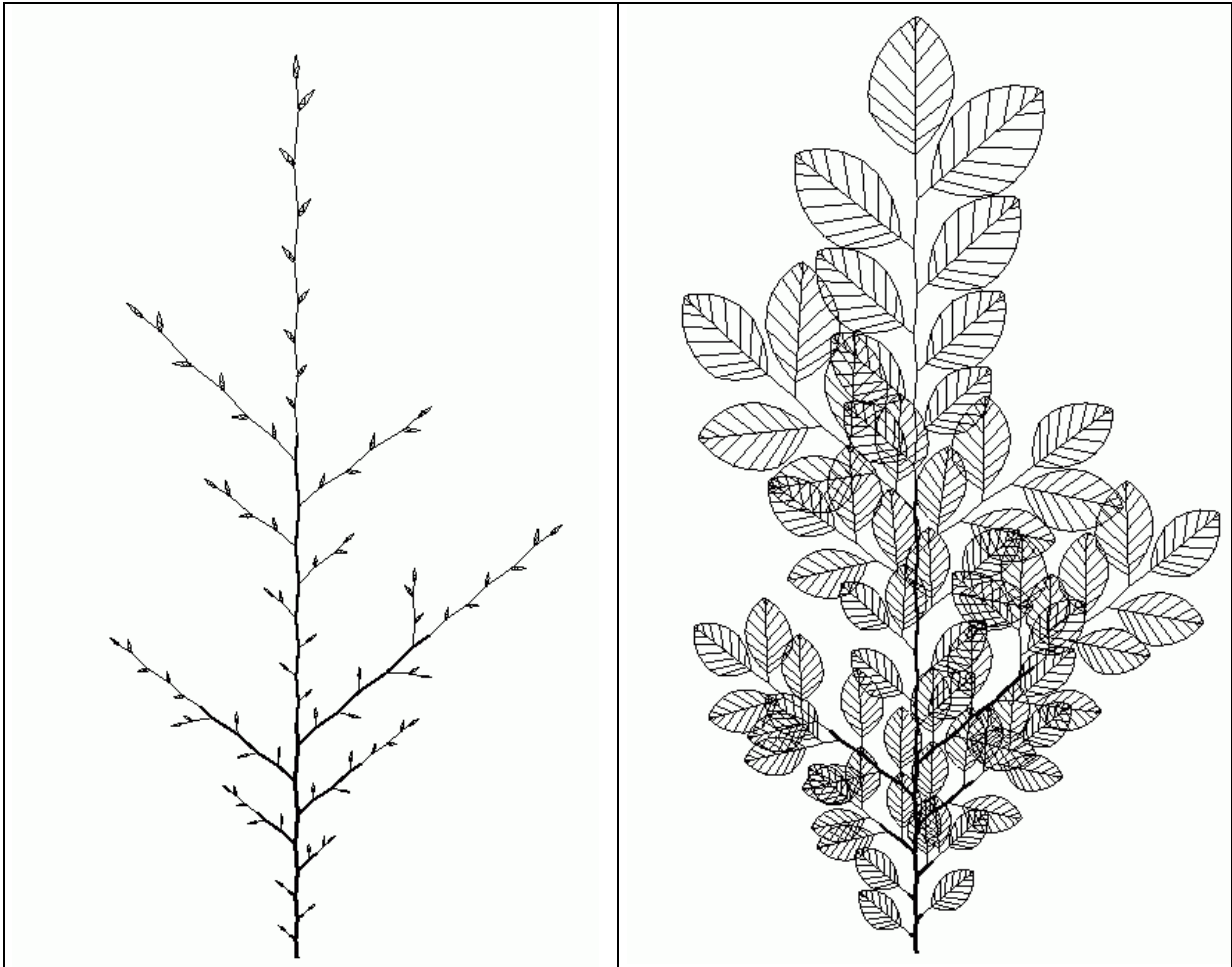




Example mint (by Prusinkiewicz & Lindenmayer):



Beech twigs:



Development of flowering plants:

