

Seminar "Auswertung von 3D-Daten"

Themenliste

Termin		Text(e)
12. 11.	<i>Thema 1</i>	Kamerakalibrierung (Klette et al. S. 41-63)
	<i>Thema 2 *</i>	Geometr. Grundlagen und Restriktionen zur Korrespondenzanalyse, Analyse mit mehr als 2 Kameras (Klette et al. S. 131-145 + 165-168)
19. 11.	<i>Thema 3 *</i>	Korrespondenzanalyse (Klette et al. S. 145-164)
	<i>Thema 4</i>	Bernardini & Rushmeier (2002): The 3D model acquisition pipeline
26. 11.	<i>Thema 5 *</i>	Seitz & Kim (2002): The space of all stereo images
	<i>Thema 6</i>	Seitz et al. (2002): Omnivergent stereo
3. 12.	<i>Thema 7 *</i>	Amenta et al. (2001): The power crust + Amenta et al. (HTML): Power crust, unions of balls...
	<i>Thema 8</i>	Zheng (1994): Acquiring 3-D models from sequences of contours
10. 12.	<i>Thema 9</i>	Noborio et al. (1988): Construction of the octree approximating three-dimensional objects by using multiple views
	<i>Thema 10*</i>	Gong & Yang (2002): Genetic-based stereo algorithm and disparity map evaluation
7. 1.	<i>Thema 11</i>	Dornaika & Chung (2000): Cooperative stereo-motion: Matching and reconstruction
	<i>Thema 12*</i>	Roth (1999): Registering two overlapping range images + Edelsbrunner (1998): Shape reconstruction with Delaunay complex (nur Teil 1)
14. 1.	<i>Thema 13*</i>	Johnson & Kang (1996+1997): Registration and integration of textured 3-D data (<i>für 2 Personen</i>)
	<i>Thema 14*</i>	
21. 1.	<i>Thema 15</i>	Kay & Caelli (1994): Inverting an illumination model from range and intensity maps
	<i>Thema 16*</i>	Neugebauer & Klein (1999): Texturing 3D models of real world objects from multiple unregistered photographic views
28. 1.	<i>Thema 17*</i>	Bernardini et al. (2001): High-quality texture reconstruction from multiple scans
	<i>Thema 18</i>	Johnson & Hebert (1999): Using spin images for efficient object recognition in cluttered 3D scenes
4. 2.	<i>Thema 19*</i>	Sumi et al. (2002): 3D object recognition in cluttered environments by segment-based stereo vision
	<i>Thema 20</i>	Stevens & Beveridge (2000): Localized scene interpretation from 3D models, range, and optical data

Themen mit " * " werden mit Priorität vergeben.

Weitere Themen zur Auswahl (bei besonderem Interesse):

Thema 21: Achour & Mahiddine (2002): Hopfield neural network based stereo matching algorithm

Thema 22: Eggert et al. (1998): Simultaneous registration of multiple range views for use in reverse engineering of CAD models

Thema 23: Soucy & Laurendeau (1995): A general surface approach to the integration of a set of range views